

DM Optimization

Piecewise constant denoising

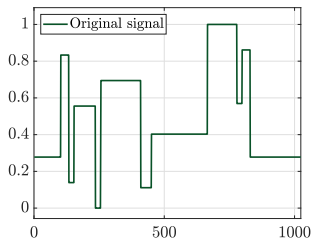
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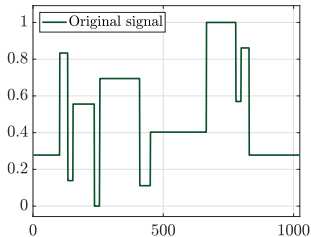
Piecewise noisy signal

Ground truth

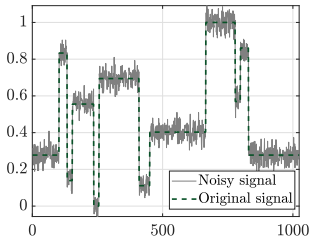


Piecewise noisy signal

Ground truth



Gaussian noise with $\sigma = 0.04$



Purpose: recover the true signal with *sharp* transitions

Denoising by functional minimization

Regularized scheme

D : differential operator, $\|\cdot\|_p$: ℓ_p -norm

$$\hat{x}_\lambda = \arg \min_{x \in \mathbb{R}^N} \frac{1}{2} \|x - y\|_2^2 + \lambda \|Dx\|_p^p$$

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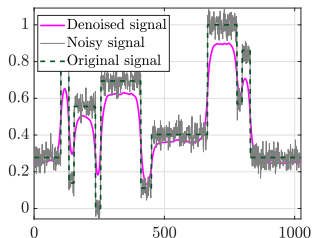
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Tikhonov regularizer $\|Lx\|_2^2$

Smooth: gradient descent



X fuzzy transitions

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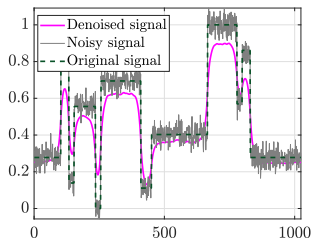
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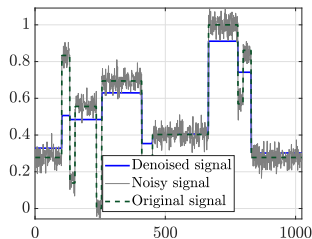
Smooth: gradient descent



✗ fuzzy transitions

Total Variation $\|Lx\|_1$

Nonsmooth: proximal algorithm



✓ sharp transitions

Formulation of the problem

Piecewise denoising

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General form:

$$\hat{x} = \arg \min_{x \in \mathbb{R}^N} f(x) + g(Lx)$$

f smooth, g nonsmooth.

Why turning to the *dual* problem?

Forward-backward algorithm

$(\forall n \in \mathbb{N}) \quad \lambda_n = 1$

$$x_{n+1} = \text{prox}_{\gamma g \circ L}(x_n - \gamma \nabla f(x_n))$$

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Primal problem

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Piecewise denoising

$$\triangleright f^*(z) = \frac{1}{2} \|y + z\|_2^2 - \frac{1}{2} \|y\|_2^2$$

constant

$$\triangleright g_\lambda^*(u) = \iota_{\|\cdot\|_\infty \leq \lambda}(u)$$

$$\hat{u}_\lambda \in \operatorname{Argmin}_{u \in \mathbb{R}^N} \frac{1}{2} \|y - L^*u\|_2^2 + \iota_{\|\cdot\|_\infty \leq \lambda}(u)$$

Link between the *primal* and the *dual* solutions

$$-L^* \hat{u} \in \partial f(\hat{x})$$

and $L\hat{x} \in \partial g^*(\hat{u})$

Link between the *primal* and the *dual* solutions

$$-L^*\hat{u} \in \partial f(\hat{x}), \partial f(\hat{x}) = \{\nabla f(\hat{x})\} \quad \text{and} \quad L\hat{x} \in \partial g^*(\hat{u})$$

Piecewise denoising

Gradient of the data-fidelity term: $\nabla f(\hat{x}) = x - y$

$$\blacktriangleright -L^*\hat{u}_\lambda = \hat{x}_\lambda - y \quad \iff \quad \hat{x}_\lambda = y - L^*\hat{u}_\lambda$$

Proximity operators

► ℓ_1 norm

$$\begin{aligned}
 x_{\text{prox}} &= \text{prox}_{\lambda \|\cdot\|_1}(x) \\
 &\iff \\
 (\forall i \in \{1, \dots, N\}) \quad x_{\text{prox}}^{(i)} &= \max \left\{ 0, 1 - \frac{\lambda}{|x^{(i)}|} \right\} x^{(i)}
 \end{aligned}$$

► quadratic data-fidelity term

$$x_{\text{prox}} = \text{prox}_{\frac{\gamma}{2} \|\cdot - y\|_2^2}(x) \iff x_{\text{prox}} = \frac{x + \gamma y}{1 + \gamma}$$

Proximity operators

- ▶ squared norm composed with a linear operator

$$x_{\text{prox}} = \text{prox}_{\frac{\gamma}{2} \|y - L^* \cdot\|_2^2}(x) \iff x_{\text{prox}} = (\text{Id} + \gamma LL^*)^{-1}(x + \gamma Ly)$$

Implementation of *dual forward-backward* algorithm

$$\hat{u}_\lambda \in \underset{u \in \mathbb{R}^N}{\text{Argmin}} \underbrace{\frac{1}{2} \|y - L^* u\|_2^2 + \iota_{\|\cdot\|_\infty \leq \lambda}(u)}_{:=h(u)}$$

- ▶ $h \in \Gamma_0(\mathbb{R}^N)$ differentiable, with gradient $\nabla h(u) = L(L^* u - y)$

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Measure convergence:

- ▶ *dual* functional $\mathcal{D}_n = 1/2 \|y - L^* u_n\|_2^2 - 1/2 \|y\|_2^2 + \iota_{\|\cdot\|_\infty \leq \lambda}(u_n)$

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- ▶ *duality gap* $\mathcal{G}_n := \mathcal{P}_n - \mathcal{D}_n \rightarrow 0$

Measuring the quality of the solution

SNR (Signal-to-Noise Ratio)

$$\text{PSNR}(\bar{x}, \hat{x}) := 20 \log_{10} \left(\frac{\|\bar{x}\|_2^2}{\|\hat{x} - \bar{x}\|_2^2} \right)$$

\bar{x} : ground truth, \hat{x} : denoised signal

High SNR indicates good estimation performance.

Interesting questions to investigate

For each *algorithm*

- ▶ does-it converge?

convergence of *primal* and *dual* functionals, *duality gap*, SNR

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For *one* given algorithm and choice of parameters

- ▶ influence of regularization parameter λ

which value of λ leads to the largest final SNR?